

Schmitt Trigger with Controllable Hysteresis Using Current Conveyors

Jiri Misurec and Jaroslav Koton

Abstract—Active elements working in the current or mixed mode are still attractive for the design of analog functional blocks. The current conveyor (CC) was defined already in 1968. This paper deals with hysteresis comparators using second generation current conveyor. The comparator is basically a pulse circuit. In these circuits, the maximum rate of change in the output voltage is required during switching from one state to another. In comparators with operational amplifiers the switching time is given by the slew rate of the operational amplifier used, which is not too high. If a current conveyor is used, the time of switching the comparator gets shorter. The comparator is capable to operate at a higher frequency bands and if it is used, for example, in converters, a higher operating frequency can be reached. The connection of an inverting and a non-inverting comparator with adjustable hysteresis is shown as a practical implementation. Using the AD844, results of experimental measurements are presented that confirm the theoretical assumptions and the results of computer simulation.

Keywords—Current conveyor, analog circuit design, hysteresis comparator.

I. INTRODUCTION

The current conveyors as active elements are known since 1968 [1], when Smith and Sedra presented the first-generation current conveyor (CCI). Later on the the second- and third-generation current conveyors have been designed [2], [3]. These elements are now with advantage used in applications, where the wide bandwidth or current output response is necessary. Nowadays, different types of current conveyors are described that are mostly based on the CCII, e.g. current controlled CC (CCCII) [17], differential voltage CC (DVCC) [18], or electronically tunable CC (ECCII) [19], [20].

The application possibilities of current conveyors are mostly presented on linear circuit design, e.g. frequency filters [4]–[7] or immittance simulators [8]–[11]. However, the CCII can be used to implement other functional blocks, such as Schmitt trigger circuit, by creating a regenerative feedback that takes part of the output voltage from terminal Z and applies it to the Y terminal of the active element [12], [13]. Schmitt Triggers based on other active elements such as Current Through Transconductance Amplifier (CTTA) or Current Differencing Transconductance Amplifier (CDTA) can be found e.g. in [14], [15].

In this paper we use simple second-generation current conveyors to implement Schmitt trigger with inverting and non-inverting hysteresis loop. First basic circuit topology is described that is subsequently supplemented by and digital-to-

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analog converter with reference input enabling digital control the value of hysteresis of the Schmitt trigger. The behavior of the proposed circuit is analyzed both by SPICE simulations and experimental measurements showing the performance of the Schmitt trigger.

II. SECOND-GENERATION CURRENT CONVEYOR AND ITS IMPLEMENTATION

Generally, in the second-generation of current conveyors, terminal Y is only a voltage terminal having infinite input impedance in theory. The X port is the current input and the current transfer from port X to port Y is zero, from X to Z it is unity. A three-port is involved here (see Fig. 1), the matrix representation of which is given by relations:

$$\begin{bmatrix} V_X \\ I_Y \\ I_Z \end{bmatrix} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} I_X \\ V_Y \\ V_Z \end{bmatrix}. \quad (1)$$

Its advantageous properties and application possibilities have grown with the development of circuits and systems in the current mode. Second-generation current conveyors have come to feature prominently in circuit structures of some commercially manufactured circuits. The AD844 circuit is a transimpedance amplifier (Analog Devices). In its internal structure there is a CCII+ second-generation current conveyor. A high-impedance outlet is important here, which is used as port z of the CCII+ conveyor. The internal connection of the circuit is shown in Fig. 2(a), the schematic symbol of the AD844 circuit in the PSpice program is in Fig. 2(b), and the ideal model is in Fig. 2(c).

It is evident from the equivalent circuit connection that its internal connection consists of two voltage followers and one current follower. Current I_{IN} flows via input resistance R_{IN} (the input resistance of low-impedance terminal is ca. 50 Ω). This current is detected by the current follower and transferred to the transimpedance terminal.

The current passage through the so-called transimpedance produces a voltage, which is conveyed to the compensation terminal. On this terminal the output current I_Z of the current conveyor is obtained too. For the sake of load separation

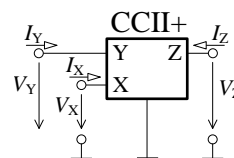


Fig. 1. Schematic symbol of CCII+ second-generation current conveyor

a voltage follower is included on the voltage output of transimpedance amplifier. However, in the case of current conveyor the voltage output is not made use of. The transimpedance models the impedance of output terminal Z and is formed by a parallel combination of resistance R_t (its magnitude is ca. 3 M Ω) and capacitance C_t (cca. 4.5 pF). The output impedance of the transimpedance terminal of this current source is high.

The output circuits of comparators are in the nature of pulse circuits and thus a maximum rate of change in the output voltage is usually required in comparison. This parameter has a direct influence on the switching time. In the classical comparator with operational amplifier the switching time is given by the slew rate of the operational amplifier used. In comparators with current conveyors the switching time should be substantially shorter.

III. HYSTERESIS COMPARATOR WITH CCII+

Similarly as in [12], transimpedance amplifiers AD844 [16] including CCII+ were used to implement the comparator. The schematic diagram of a hysteresis comparator implemented using two CCII+ conveyors is shown in Fig. 3.

From the connection of non-inverting hysteresis comparator with operational amplifier the equivalent connection of non-inverting or inverting hysteresis comparator with CCII+ can be derived. The connection given in Fig. 3 combines two possibilities. The circuit part containing the CCII+A current conveyor represents the non-inverting hysteresis comparator while the part containing the CCII+B current conveyor performs the function of an inverting hysteresis comparator. Then output voltage V_{OUT1} is the output of the non-inverting

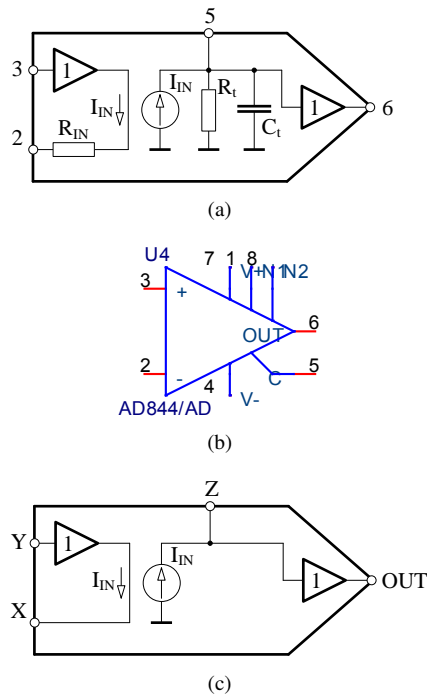


Fig. 2. (a) Internal connection of circuit AD844 [16], (b) symbol of circuit AD844 in PSpice program, (c) idealized model of circuit AD844

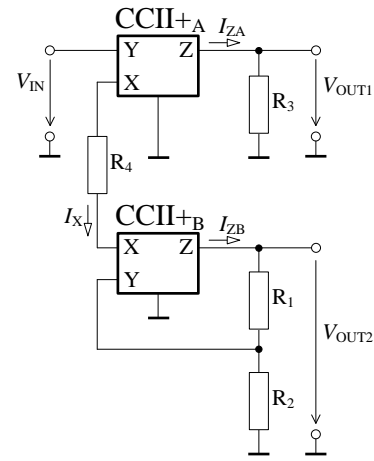


Fig. 3. Non-inverting and inverting hysteresis comparator with two CCII+s

hysteresis comparator, and output voltage V_{OUT2} is the output of inverting hysteresis comparator.

To describe the activity and determine the values of positive comparison voltage $+V_P$ and negative comparison voltage $-V_N$ of the comparator from Fig. 3 we will start from the knowledge of CCII+ in the AD844 circuit as given above. In this case the most important parameter of CCII+ is the magnitude of the transimpedance formed by a parallel connection of resistance R_t and capacitance C_t . These elements form the impedance of output terminal Z. The output resistance R_X of low-impedance terminal X also needs to be taken into consideration.

Consider that the output voltage V_{OUT1} can acquire values $+V_{OUT_SAT}$ or $-V_{OUT_SAT}$, with the output voltage V_{OUT2} always acquiring the opposite values, i.e. $-V_{OUT_SAT}$ and $+V_{OUT_SAT}$. The outputs V_{OUT1} and V_{OUT2} are mutually complementary.

Consider that the output voltage V_{OUT2} of conveyor CCII+B has a maximum positive level, i.e. $V_{OUT2} = +V_{OUT_SAT}$, in which case the voltage $+V_P$ on port Y of current conveyor CCII+B is given by the relation:

$$+V_P = +V_{OUT_SAT} \frac{R_2}{R_1 + R_2} = +V_{OUT_SAT} \beta. \quad (2)$$

If on the contrary there is on the output of conveyor CCII+B a minimum negative level, $V_{OUT2} = -V_{OUT_SAT}$, then the voltage on port Y of this conveyor is:

$$-V_N = -V_{OUT_SAT} \frac{R_2}{R_1 + R_2} = -V_{OUT_SAT} \beta. \quad (3)$$

By the definition of current conveyor CCII+ it holds that $V_X = V_Y$, so that the voltage on port Y will be repeated also on port X of CCII+B. Therefore, the current flowing into terminal X can be expressed as:

$$I_X = \frac{V_{IN} - V_{OUT_SAT} \beta}{2R_X + R_4}. \quad (4)$$

From the conveyor definition it further follows that the output current of conveyor CCII+A is $I_{ZA} = I_X$, and the output current of conveyor CCII+B is $I_{ZB} = -I_X$. The output voltage

of conveyor CCII+_A is then given by the relation:

$$V_{ZA} = V_{OUT1} = \frac{V_{IN} - V_{OUT_SAT}\beta}{2R_X + R_4} \frac{R_t}{1 + sR_tC_t} \quad (5)$$

and the output voltage of conveyor CCII+_B is:

$$V_{ZB} = V_{OUT2} = -\frac{V_{IN} - V_{OUT_SAT}\beta}{2R_X + R_4} \frac{R_t}{1 + sR_tC_t}, \quad (6)$$

where $s = j\omega$, whereas ω is the angular frequency. Simplified relations can be obtained in the form of

$$V_{ZA} = V_{OUT1} = \frac{R_t}{2R_X + R_4} (V_{IN} \mp V_{OUT_SAT}\beta), \quad (7)$$

$$V_{ZB} = V_{OUT2} = -\frac{R_t}{2R_X + R_4} (V_{IN} \mp V_{OUT_SAT}\beta), \quad (8)$$

where the negative sign “-” and positive sign “+” within the parentheses denote the state of comparator output voltages V_{OUT1} and V_{OUT2} . If $V_{OUT1} = -V_{OUT_SAT}$, then $V_{OUT2} = +V_{OUT_SAT}$, and if $V_{OUT1} = +V_{OUT_SAT}$ then $V_{OUT2} = -V_{OUT_SAT}$.

After switching the conveyor outputs to the values $V_{OUT1} = -V_{OUT_SAT}$ and $V_{OUT2} = +V_{OUT_SAT}$ the input voltage V_{IN} must drop below the value $-V_{OUT_SAT}\beta$. The comparator hysteresis is defined as the difference between the positive and the negative comparison level of input voltage and is thus given by the relation:

$$\begin{aligned} h &= +V_P - (-V_N) = +V_{OUT_SAT}\beta - (-V_{OUT_SAT}\beta) = \\ &= 2\beta V_{OUT_SAT}. \end{aligned} \quad (9)$$

IV. COMPUTER SIMULATION OF HYSTERESIS COMPARATOR WITH CCII+

The operation of the comparator from Fig. 3 was tested in computer simulation. In the MicroCap simulation program the model of the AD844AD circuit will be used. The circuit parameters set for the simulation were: supply voltage $V_{CC} = \pm 15$ V, saturation voltage $V_{OUT_SAT} = 10$ V, the resistance values chosen are $R_1 = R_2 = 10$ k Ω , consequently $\beta = 0.5$, $R_3 = 20$ k Ω , and $R_4 = 1$ k Ω . The calculated value of comparison voltage is $+V_P = 5$ V and the comparator hysteresis is then $h = 10$. For the chosen $V_{IN} = 10$ V the output current magnitudes of the two current conveyors are $I_{ZA} = 4.5$ mA and $I_{ZB} = -4.5$ mA.

Simulation results are given for non-inverting comparator in Fig. 4(a), and for inverting comparator in Fig. 4(b). Arrowheads in the waveforms follow the direction of the change in input voltage V_{IN} . As can be seen, the circuit performs the expected function. The circuit part containing the CCII+_B fulfills the function of inverting hysteresis comparator, the part with CCII+_A performs the function of non-inverting hysteresis comparator.

V. DIGITAL CONTROL OF HYSTERESIS AND EXPERIMENTAL MEASUREMENTS

For the digital control of hysteresis magnitude the comparator connection including a CCII+ was proposed as given in Fig. 5. The initial basic connection given in Fig. 3 was complemented with a multiplier with digital-to-analog converter AD7533 [21], operational amplifier LM741 (which is connected as a voltage follower), and a third CCII+ current conveyor AD844. Voltage from the divider R_1 - R_2 is conveyed to the multiplier, where it is multiplied by the value of a 10-bit input word D , which sets the hysteresis magnitude. Therefore, it is necessary to multiply the relations (2), (3) and (9) by the value D . The value D expresses the binary fraction value of 10-bit digital input word DAC; examples of calculating D for some of the combinations are given in Table I. In the comparator connection implemented, hysteresis can be set in an interval $h = 0$ V to $h = 12.125$ V, in dependence on the set combination of 10-bit digital word D .

The measured waveforms for the control word $D = 1111111111$ is given in Fig. 6. For this value of the number D the maximum value of comparator hysteresis is obtained, $h = 12.125$ V. For $D = 1000000000$ the waveform is shown in Fig. 7 while for $D = 0000000001$ it is shown in

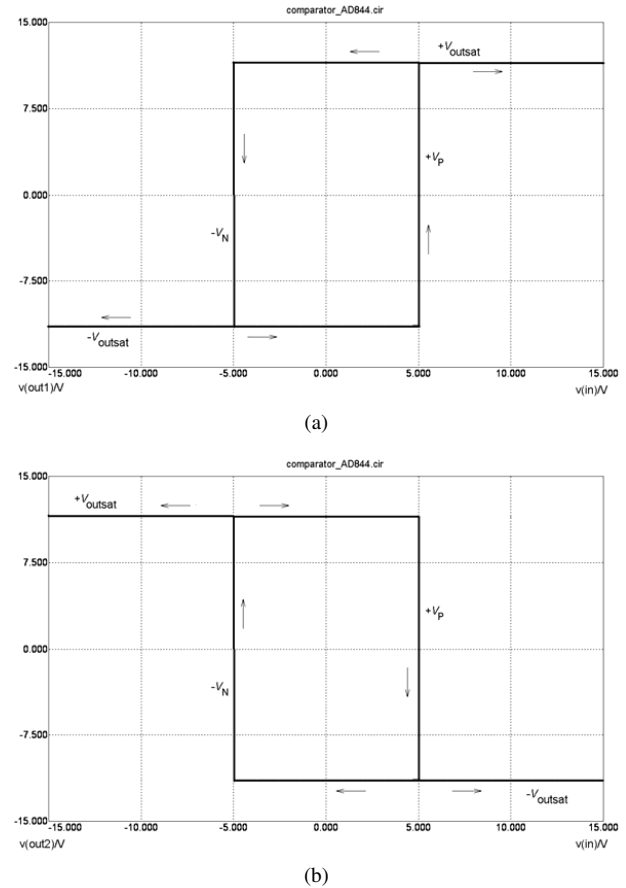


Fig. 4. (a) non-inverting, (b) inverting waveform of hysteresis characteristic of comparator from Fig. 3

TABLE I
BINARY FRACTION REPRESENTATION OF SOME COMBINATIONS OF 10-BIT
DAC INPUT DIGITAL INPUT BINARY FRACTION VALUE

Digital input (MSB → LSB)	Binary fraction value
1111111111	1023/1024
1000000001	513/1024
1000000000	512/1024
0111111111	511/1024
0000000001	1/1024
0000000000	0/1024

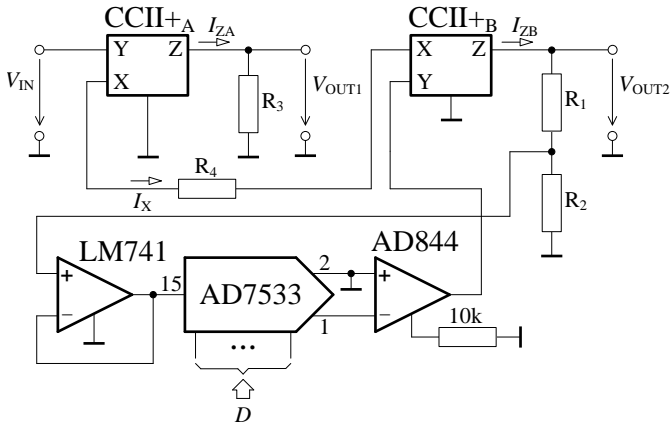
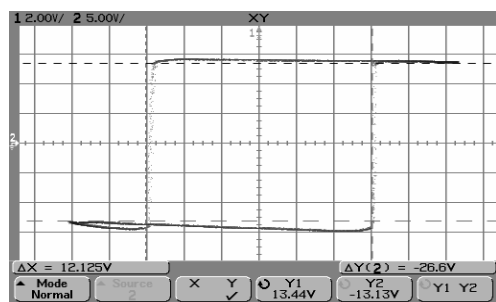
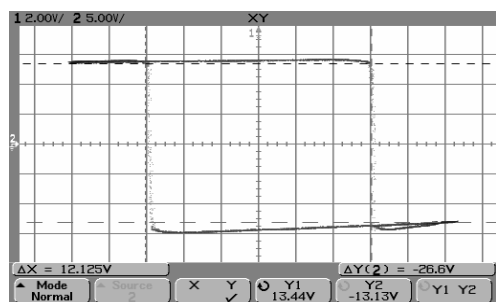


Fig. 5. Design schematic of comparators with variable hysteresis



(a)

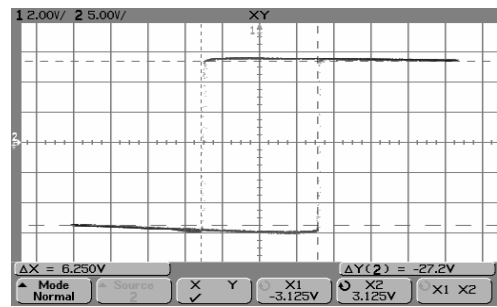


(b)

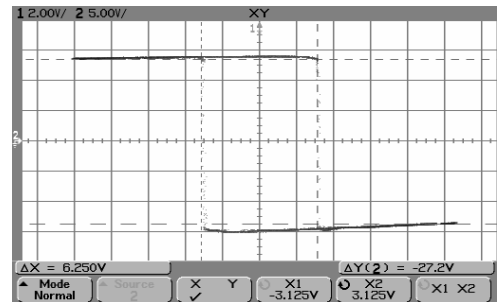
Fig. 6. Hysteresis loop for $D = 1111111111$, (a) non-inverting comparator (b) inverting comparator

Fig. 8. The value of hysteresis h in the comparator is given by the parameter of ΔX cursors in the left bottom corner while the parameter ΔY in the right bottom corner gives the value of $2V_{OUT_SAT}$. The testing input signal was a sinusoidal waveform of frequency 2.2 kHz.

With increasing frequency of the input signal the magnitude of the hysteresis value changes. The waveforms of

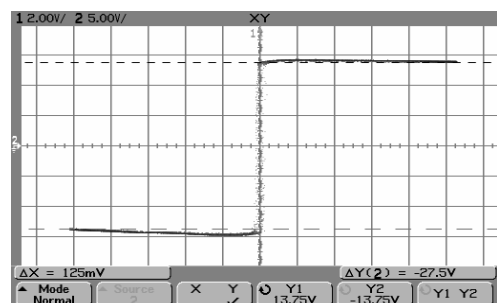


(a)

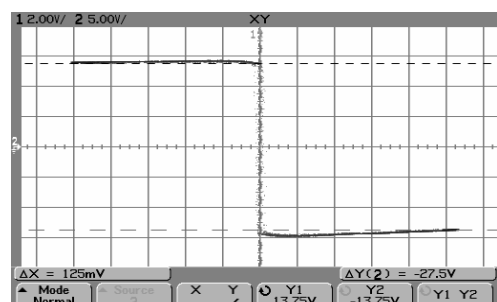


(b)

Fig. 7. Hysteresis loop for $D = 1000000000$, (a) non-inverting comparator (b) inverting comparator



(a)



(b)

Fig. 8. Hysteresis loop for $D = 0000000001$, (a) non-inverting comparator (b) inverting comparator

output signal of inverting comparator at input signal frequency 5.5 kHz and D set to 0000000001 is given in Fig. 9(a) while Fig. 9(b) gives the waveform for input frequency 650 kHz. The two waveforms can be compared with the oscillograms given in Fig. 8(b). For the above value of input word D the hysteresis should be $h = 125$ mV but the actual hysteresis value is 300 mV. If the input signal frequency increases, the

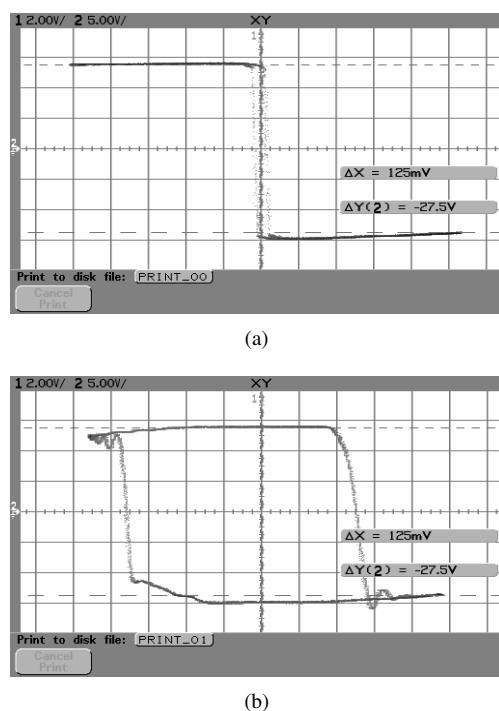


Fig. 9. Hysteresis loop of inverting comparator for $D = 0000000001$, (a) frequency $f = 5.5$ kHz (b) frequency $f = 650$ kHz

hysteresis loop gets more extended and the dynamic properties of current conveyors come to be fully shown. At the time of switching, noticeable overshooting can be observed on the waveforms. This has a considerable effect on comparator precision, showing in the utilizable frequency band of comparator with AD844.

VI. CONCLUSION

The paper presents the solution of a voltage comparator with current conveyors CCII+. A theoretical analysis and computer simulation were performed and a digitally controlled inverting and non-inverting comparator has been proposed. The comparator has some pulse circuit elements and therefore a maximum rate of output voltage change is usually required. Measuring on an experimental specimen shows the results obtained. The values of hysteresis h measured for three chosen combinations of D , i.e. full extent of h , half the extent of h , and the least value of h , were compared with calculated values. The deviation from these values was cca. 3% for individual values of D . In the connection given, there is evidently a drop in voltage, obviously due to the AD7533 multiplier. Measuring the comparator without multiplier did not exhibit this error. Thus the good functionality of the comparator was verified and the advantage of the current mode was shown. Further work will focus on obtaining a higher operating frequency.

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